A Novel Modified-T Equivalent Circuit for Modeling LTCC Embedded Inductors With a Large Bandwidth

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Abstract—This paper presents a new modified-T model for three-dimensional inductors embedded in the multilayer low-temperature cofired-ceramic substrate with a remarkably large bandwidth. This model combines a core circuit, a five-element modified-T model, to include the effects of a transmission line with an electrical length up to π , and several resonators to consider the effects due to coil coupling and the finite ground plane. It is emphasized that most of the elements in this equivalent-circuit model can be extracted directly from the measured S-parameters. Compared to the conventional PI-section model that is valid only up to the fundamental self resonant frequency (SRF), this model can include more higher-order SRFs and ground resonant frequencies effectively, which results in several times larger bandwidth.

Index Terms—Embedded inductor, inductor model, low-temperature cofired-ceramic (LTCC) inductor, three-dimensional (3-D) inductor.

I. INTRODUCTION

OW-TEMPERATURE cofired-ceramic (LTCC) embedded inductors can be viewed as passive interconnects that are conventionally modeled using PI- or T-section models [1]–[3]. Although several additional capacitances and resistances have been included to account for coupling and loss in the coil and substrate, these models are still narrow-banded due to the nature of PI- and T-section models that cannot represent a transmission line over a wide frequency range effectively. The distributed model using multiple PI- or T-sections can be applied to overcome this drawback [4], [5]. However, it is difficult to find these distributed elements from the measured *S*-parameters without using intensive optimization. This is because the measured *S*-parameters providing the overall frequency response for an equivalent distributed circuit lack useful information on the segmentation of the individual section.

This paper breaks through the above-mentioned modeling barriers by inventing a five-element modified-T circuit that can approximate very closely a lossless transmission line with electrical length up to π , the well-known period of transmission-line effects. In conjunction with several resonators, this modified-T circuit can be expanded to model real LTCC em-

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 $\overbrace{C_0, \theta = \omega \tau}^{C_p} \approx \overbrace{L_s}^{C_p}$

Fig. 1. Five-element modified-T equivalent circuit for modeling a lossless transmission line with electrical length up to π .

bedded inductors over a large bandwidth. Although such a modified-T equivalent circuit to be established needs quite a number of circuit elements, our modeling approach still shows amazing efficiency by skillfully formulating with all kinds of resonant frequencies in an element-extraction procedure. As a result, all the reactive elements in the model can be extracted from the measured S-parameters directly. In the demonstration, three different types of LTCC embedded inductors including spiral, meander, and vertically stacked spiral have been measured with two-port S-parameters from which both modified-T and PI-section equivalent circuits are established for comparison. The modified-T model is superior to the PI-section model quite obviously with a several times larger amount of modeling bandwidth.

II. MODIFIED-T MODEL FOR TRANSMISSION LINES

In our previous work [6], we have demonstrated the mathematical extraction procedure to find the circuit elements in an equivalent modified-T model for ideal transmission lines, as shown in Fig. 1. The circuit elements can be expressed in terms of transmission-line parameters as

$$L_s = Z_0 \tau \left(\frac{1}{4} + \frac{1}{\pi^2}\right) \tag{1}$$

$$L_m = Z_0 \tau \left(\frac{1}{4} - \frac{1}{\pi^2}\right) \tag{2}$$

$$C_s = \frac{\tau}{Z_0} \tag{3}$$

$$C_p = \frac{\tau}{Z_0 \pi^2}.$$
 (4)

For example, we compare the simulated two-port S-parameters from the transmission-line configuration shown in Fig. 2, and those from its equivalent modified-T model whose circuit elements can be found according to (1)–(4). Fig. 3 shows a comparison of these S-parameters on a Smith chart under various normalized characteristic impedances (z_0) with a sweep of electrical length from zero to π . It can be seen that both S-parameter responses are almost identical. In Fig. 4, the mean and maximum absolute values for the difference of S-parameters in the

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Fig. 2. Transmission-line configuration used for comparing its two-port S-parameters with those in an equivalent modified-T model. Assume $\tau = 100$ ps for this case.



Fig. 3. Comparison of S_{11} and S_{21} on a Smith chart between the transmission-line circuit shown in Fig. 2 and its equivalent modified-T model with a sweep of electrical length from zero to π .



Fig. 4. Maximum and mean absolute values versus normalized characteristic impedance for the *S*-parameter differences between the transmission-line circuit shown in Fig. 2 and its equivalent modified-T model.

range of electrical length from zero to π are shown as a function of z_0 . One can see that the mean and maximum errors are less than 0.04 and 0.1, respectively, for all possible values of z_0 . It is, therefore, to be believed that the proposed modified-T model can very closely represent a lossless transmission-line section with a wide range of characteristic impedance and an electrical length up to π .



Fig. 5. Expanded modified-T equivalent circuit for modeling an LTCC embedded inductor.

III. MODIFIED-T MODEL FOR LTCC EMBEDDED INDUCTORS

As suggested in Fig. 5, the modified-T equivalent circuit can be further expanded to model the three-dimensional (3-D) inductors embedded in a multilayer LTCC substrate. Several *LC* resonators have been added to account for the self and ground resonant phenomena. The formulation starts with a derivation of the corresponding Y network parameters given as

$$Y_{11} = \frac{j\omega L_{s2} + Z_g}{-\omega^2 \left(L_{s1}L_{s2} - L_m^2\right) + j\omega Z_g (L_{s1} + L_{s2} + 2L_m)} + Y_p$$
(5)

$$Y_{22} = \frac{j\omega L_{s1} + Z_g}{-\omega^2 \left(L_{s1}L_{s2} - L_m^2\right) + j\omega Z_g (L_{s1} + L_{s2} + 2L_m)} + Y_p$$
(6)

 $Y_{12} = Y_{21}$

$$=\frac{j\omega L_m - Z_g}{-\omega^2 (L_{s1}L_{s2} - L_m^2) + j\omega Z_g (L_{s1} + L_{s2} + 2L_m)} - Y_p$$
(7)

where

$$Z_{g} = \left\{ j\omega C_{s}b + \left\{ j\omega L_{g} + [j\omega C_{s}(1-b)]^{-1} \right\}^{-1} \right\}^{-1}$$
(8)
$$Y_{p} = \left\{ j\omega L_{p} + (j\omega C_{p}a)^{-1} \right\}^{-1} + \left\{ j\omega L_{p1} + [j\omega C_{p}(1-a)]^{-1} \right\}^{-1}.$$
(9)

Note that Z_g denotes the series-feedback resonator impedance, while Y_P denotes the total admittance for all parallel-feedback resonators. In the extraction of circuit elements, we use the real *S*-parameter measurement results of a 6.8-nH LTCC embedded inductor to illustrate that the whole procedure can be carried out efficiently and reliably in the following steps.

Step 1. Formulation With Parallel and Series Resonant Frequencies

First, a new parameter Y_A composed of Y network parameters is defined as

$$Y_{A} = Y_{11} + Y_{22} - 2Y_{12}$$

= $\frac{j\omega(L_{s1} + L_{s2} - 2L_m) + 4Z_g}{-\omega^2 (L_{s1}L_{s2} - L_m^2) + j\omega Z_g (L_{s1} + L_{s2} + 2L_m)} + 4Y_p.$ (10)



Fig. 6. Determination of parallel and series resonant frequencies from the imaginary part of Y_A .

Assuming $L_{s1} \approx L_{s2}$ and simplifying (10) gives

$$Y_A \approx \frac{4}{j\omega(L'_{s1} + L'_{s2})} + 4Y_p \tag{11}$$

where

$$L'_{s1} = L_{s1} + L_m \tag{12}$$

$$L'_{s2} = L_{s2} + L_m. (13)$$

One can see from (11) that such a new parameter can get rid of the factor of ground resonator impedance (Z_q) under the assumption $L_{s1} \approx L_{s2}$. According to our observation, (11) is also often true even if L_{s1} is not so close to L_{s2} . This is because Z_q usually behaves as the dominant order in the fractional term of (10) and can be factored out finally. The sum value $(L'_{s1} + L'_{s2})$ that appears in (11) represents the total inductance of the inductor. Generally speaking, this value can be extracted from the equivalent PI-section model quite robustly at low frequencies. Therefore, the information coming from Y_A is mainly related to the parallel-feedback resonators in parallel connection with the total inductance, which will include multiple parallel and series resonances. Fig. 6 shows the imaginary part of the Y_A -parameter that can be obtained using conversion from S into Y network parameters. One can find two zeros and two poles within the measurement frequency range. The root positions identify the first and second parallel resonant frequencies $\omega_p/2\pi$ and $\omega_{p1}/2\pi$, while the pole positions identify the first and second series resonant frequencies $\omega_s/2\pi$ and $\omega_{s1}/2\pi$. It is noted that one pair of parallel and series resonances in the Y_A -parameter contributes to a self-resonance (transmission zero) in the S_{21} -parameter with a self resonant frequency (SRF) in between the parallel and series resonant frequencies. When formulated with these four identified resonant frequencies, the circuit elements in the parallel-feedback resonators can be expressed as

$$C_{p} = \left\{ \left(L_{s1}' + L_{s2}' \right) \left[a \left(\omega_{p}^{-2} - \omega_{s}^{-2} \right)^{-1} + (1 - a) \left(\omega_{p}^{-2} - \omega_{s1}^{-2} \right)^{-1} \right] \right\}^{-1}$$
(14)

$$L_p = \left(a\omega_s^2 C_p\right)^{-1} \tag{15}$$

$$L_{p1} = \left[(1-a)\omega_{s1}^2 C_p \right]^{-1}$$
(16)



Fig. 7. Determination of half-wave frequencies and GRFs from the imaginary part or phase of Y_B .

where parameter a in (14)–(16) represents a split coefficient for the parallel-feedback resonator capacitance and can be found as shown in (17) at the bottom of the following page.

Step 2. Formulation With Half-Wave and Ground Resonant Frequencies (GRFs)

Another new parameter, i.e., Y_B , also composed of Y network parameters is defined as

$$Y_B = Y_{11} + Y_{22} + 2Y_{12}$$

=
$$\frac{j\omega(L'_{s1} + L'_{s2})}{-\omega^2 [L'_{s1}L'_{s2} - L_m(L'_{s1} + L'_{s2})] + j\omega Z_g(L'_{s1} + L'_{s2})}.$$
(18)

The purpose of using the Y_B -parameter is to remove the factor of Y_p , but maintain the factor of Z_q instead. Therefore, the information coming from Y_B is closely related to the series-feedback resonator, which will include the complete resonant effects due to the finite ground plane in an LTCC structure. Besides, the denominator in the expression of Y_B goes to zero at the half-wave frequency $(\omega_h/2\pi)$. The reason to call it half-wave frequency is because for an ideal transmission line such as a pole position, which corresponds to the frequency at which the transmission line is a half-wavelength long [6]. Fig. 7 shows the imaginary part and also the phase for the Y_B -parameter. From the frequency response of the imaginary part, one can clearly see a dominant pole that locates at the half-wave frequency. More information can be found from the phase data. In the vicinity of a half-wave frequency, the phase has a sudden drop from almost 90° to 0° . This is because two GRFs come after the half-wave frequency. The first one is the series GRF ($\omega_{gs}/2\pi$), at which Z_g approaches zero. The second one is the parallel GRF ($\omega_{qp}/2\pi$), at which Z_q approaches infinity. We can locate these frequencies according to the suggestions shown in Fig. 7. With these three newly identified half-wave frequencies and GRFs, we can formulate the mutual and ground inductances in the forms

$$L_m = \frac{L'_{s1}L'_{s2}}{L'_{s1} + L'_{s2}} - \left\{\omega_h^2 C_s b \left[1 - \frac{(1-b)\omega_{gp}^2}{\omega_h^2 - b\omega_{gp}^2}\right]\right\}^{-1}$$
(19)

$$L_g = \left[\omega_{gp}^2 C_s b(1-b)\right]^{-1} \tag{20}$$



Fig. 8. Conventional PI-section model for inductors.

where the parameter b in (19) and (20) represents another split coefficient for the series-feedback resonator capacitance and can be found as

$$b = \frac{\omega_{gs}^2}{\omega_{qp}^2}.$$
 (21)

Calculations of mutual and ground inductances in (19) and (20) require knowledge of the parameters L'_{s1} , L'_{s2} , and C_s whose quantities can be extracted at low frequencies, as will be presented in the following step. It is also noted that there is an alternative way to accurately find the capacitance split coefficients a and b through optimization with the constrains

$$0 \le a \le 1 \tag{22}$$

$$0 \le b \le 1. \tag{23}$$

Step 3. Extraction of Fundamental Elements at Low Frequencies Using PI-Section Model

The well-known PI-section model, as shown in Fig. 8, can be used to extract some fundamental elements including the main inductance and shunt capacitance in a modified-T model. The extraction summarized as follows is mainly done at low frequencies:

$$L'_{s1} + L'_{s2} \approx \frac{1}{\omega \text{Im}\{Y_{12}\}}$$
(24)

$$\frac{L'_{s1}}{L'_{s2}} \approx \frac{\operatorname{Im}\{Z_{11} - Z_{12}\}}{\operatorname{Im}\{Z_{22} - Z_{12}\}}$$
(25)

$$C_s = C_{s1} + C_{s2} \approx \frac{\operatorname{Im}\{Y_B\}}{\omega} \tag{26}$$

$$\frac{C_{s1}}{C_{s2}} \approx \frac{\operatorname{Im}\{Y_{11} + Y_{12}\}}{\operatorname{Im}\{Y_{22} + Y_{12}\}}.$$
(27)



Fig. 9. Resistances added to the modified-T or PI-section models for inclusion of the frequency-dependent losses.

The parallel capacitance C_p^\prime in an equivalent PI-section model is calculated as

$$C'_{p} = \frac{\omega_{r}^{-2}}{\left(L'_{s1} + L'_{s2}\right)}$$
(28)

where ω_r is found from $\lim\{Y_{12}(\omega_r)\} = 0$. After this step, we have found all the reactive elements in the equivalent modified-T and PI-section models analytically.

Step 4. Optimization for Resistance Values According to Frequency-Dependent Quality (Q) Factor

Some resistances are included in the equivalent modified-T or PI-section models to account for the frequency-dependent losses, as shown in Fig. 9. The series resistances R_{s1} and R_{s2} are used to model the conductor loss dominant at lower frequencies, while the parallel and ground resistances R_p and R_g are used to model the substrate loss dominant at higher frequencies. It is without controversy that the Q factor is the most representative parameter to evaluate the inductor loss. The most popular definition for the Q factor is based on the one-port inductor model with the second port grounded, and can be generally expressed as the ratio of the imaginary to real part of the input impedance [7]–[10]. Such a Q-factor definition can be further derived as a function of the input reflection coefficient expressed in terms of S-parameters, which is given as

$$Q = \frac{\operatorname{Im}\{Z_{\rm in}\}}{\operatorname{Re}\{Z_{\rm in}\}} = \frac{2\operatorname{Im}\{\Gamma_{\rm in}\}}{1 - |\Gamma_{\rm in}|^2}$$
(29)

where

$$\Gamma_{\rm in} = S_{11} - \frac{S_{12}S_{21}}{1 + S_{22}}.$$
(30)

A simple optimization scheme for resistance values used in the modified-T and PI-section models has been developed on Agilent's Advanced Design System to fit the measured Q-factor response, as shown in Fig. 10. It is noted that the frequency range of interest in optimization is up to the first SRF where

$$a = \frac{\omega_p^2 \left(1 - \frac{\omega_p^2}{\omega_{s1}^2}\right)^{-1} - \omega_{p1}^2 \left(1 - \frac{\omega_{p1}^2}{\omega_{s1}^2}\right)^{-1}}{\omega_p^2 \left[\left(1 - \frac{\omega_p^2}{\omega_{s1}^2}\right)^{-1} - \left(1 - \frac{\omega_p^2}{\omega_s^2}\right)^{-1}\right] - \omega_{p1}^2 \left[\left(1 - \frac{\omega_{p1}^2}{\omega_{s1}^2}\right)^{-1} - \left(1 - \frac{\omega_{p1}^2}{\omega_s^2}\right)^{-1}\right]}$$
(17)



Fig. 10. Comparison of the Q factor between the modified-T and PI-section models with measurements for a 6.8-nH LTCC embedded spiral-type inductor.



Fig. 11. Top and side views of a 6.8-nH spiral-type inductor embedded in a multilayer LTCC substrate and the established equivalent modified-T model.

Q factors are positive real numbers. Such an optimization takes only a few seconds using a standard PC. Within this frequency range, the measured and modeled Q factors can agree quite well through optimization.

IV. EXAMPLES

For demonstration, we have implemented three different types of embedded inductors including: 1) spiral; 2) meander; and 3) vertically stacked spiral in a 22-layer LTCC process. Each layer is 3-mil thick and the final substrate size is fixed at 120 mil \times 120 mil \times 66 mil. All inductors embedded in such an LTCC substrate are also designed with a fixed outer dimension of 120 mil \times 60 mil and have top and bottom ground planes for the purpose of suppressing electromagnetic interference (EMI). Both ground planes have a distance of 33 mil from one to the other and a total of four vias outside the inductors is 6 mil and the substrate dielectric constant is 7.8.

Fig. 11 shows the geometry of a 1.5-turn rectangular spiral inductor and the equivalent modified-T model. This device has an equivalent inductance of 6.8 nH at low frequencies. All the reactive elements in the equivalent modified-T model can be found accurately using the analytical expressions provided in Steps 1–3 of the element-extraction procedure given in Section III. The resistances used to account for the frequency-dependent losses are found through optimization, as



Fig. 12. Comparison of the magnitude of S_{11} and S_{21} in decibels between the equivalent modified-T and PI-section models with measurements for the 6.8-nH spiral-type inductor.



Fig. 13. Top and side views of a 5.6-nH meander-type inductor embedded in a multilayer LTCC substrate and the established equivalent modified-T model.

suggested in Step 4 of the procedure. In Fig. 12, we compare the S-parameter results generated from our proposed modified-T model and the conventional PI-section model with measurements within the frequency range up to 15 GHz. It can be seen that the conventional PI-section model is good only up to the fundamental SRF at 3.5 GHz. Our proposed modified-T model can catch not only the fundamental SRF, but also the GRF at 8.4 GHz and the next higher SRF at 10.6 GHz. The effective bandwidth exceeds 12 GHz, approximately four times larger than in a PI-section model. As shown in Fig. 13, the case for a meander-type inductor having an equivalent inductance of 5.6 nH at low frequencies can employ the same equivalent model structure. The modeled results shown in Fig. 14 also demonstrate that our proposed modified-T model surpasses the PI-section model quite obviously in comparison of bandwidth. Such a meander-type inductor has the fundamental SRF, GRF, and next higher SRF at 3.6, 8.4, and 12.9 GHz, respectively, which has been predicted successfully from the established modified-T model.

In the last example, shown in Fig. 15, two rectangular spiral inductors of opposite direction of rotation are stacked vertically. Each inductor has two turns of winding. The total inductance at low frequencies approaches 14.5 nH. Within the same frequency range, this inductor exhibits more SRFs and GRFs than the former two inductors. It is, therefore, required to expand in series and parallel feedback resonators of a modified-T model according to the increase of number of SRFs and GRFs, as also illustrated in Fig. 15. It is emphasized that all the reactive elements in this expanded modified-T model can still be found



Fig. 14. Comparison of the magnitude of S_{11} and S_{21} in decibels between the equivalent modified-T and PI-section models with measurements for the 5.6-nH meander-type inductor.



Fig. 15. Top and side views of a 14.5-nH vertically stacked spiral-type inductor embedded in a multilayer LTCC substrate and the established equivalent modified-T model.



Fig. 16. Comparison of the magnitude of S_{11} and S_{21} in decibels between the equivalent modified-T and PI-section models with measurements for the 14.5-nH vertically stacked spiral-type inductor.

analytically with enough numbers of the identified SRFs and GRFs. Fig. 16 shows the comparison of modeled *S*-parameters with measured results. Again, only the modified-T model can provide good accuracy in the entire frequency range up to 15 GHz.

V. CONCLUSION

Due to the feature of broad-band transmission-line characteristics, the proposed modified-T equivalent circuit is successful in modeling a variety of types of LTCC embedded inductors with a bandwidth several times larger than a conventional PI-section model. In addition, this new model structure can be constructed quite efficiently because all the reactive elements in the model can be extracted from the measured S-parameters analytically with the help of identifying SRFs and GRFs. The remaining few resistances in the model have been found through optimization to best fit the frequency-dependent Qfactor that can be also determined from the measured S-parameters. This modeling technique can be applied to any types of high-speed interconnects and should be helpful in analysis and design for compensating the discontinuity effects.

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